

# Wrap-Up and Best Practice

DWD ICON Course | July 2025 | Florian Prill, DWD



# Before you start your journey

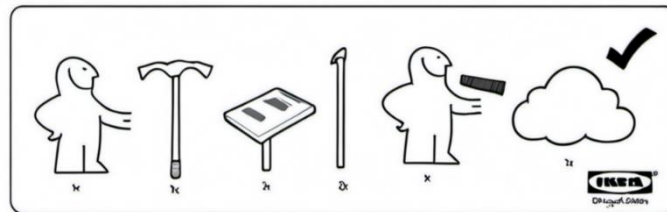
Recap of this week's lectures and exercises ...



# Before you start your journey

- Using an **HPC** makes sense, when it later comes to NWP use cases with realistic, high resolutions; running a “standard” x86 CPU cluster will simplify matters. Ideally, we recommend using the HPC platform of an ICON partner, e.g. Levante (DKRZ).
- Find out the essential **hardware parameters** (number of CPU cores, RAM). Know some details about your **compiler** and the **MPI installation**, eg. the version and compiler name.
- Necessary **libraries like Eccodes** are often available as modules, find out more!
- Explore your **file systems** (info often provided in the HPC documentation<sup>[1]</sup>). Choose a work partition for your experiments, ie. high-throughput, large-scale data, no backup.

[1] eg. <https://docs.dkrz.de/doc/levante/file-systems.html>



# Install the ICON code

- Best practice: choose the **latest Open Source release version**<sup>[1]</sup> of ICON.
- You can make it easier to create the build setup by using a pre-configured **configure wrapper**<sup>[2]</sup>. Note that you can call these with additional arguments.
- Configuration: decide whether to activate non-default sub-packages, ie. set configure switches with the prefix `--enable-xxx` or omit others. You might, for example, consider enabling the Community Interface and its Python adapter right away<sup>[3]</sup>.
- Compiler options: make sure that you **generate debugging information** for proper stack traces (at least for the first time, `-g` option).
- When using the command `make -jX`, avoid placing too much load on the front-end node by selecting an appropriate value for `X`.




<sup>[1]</sup> <https://gitlab.dkrz.de/icon/icon-model>

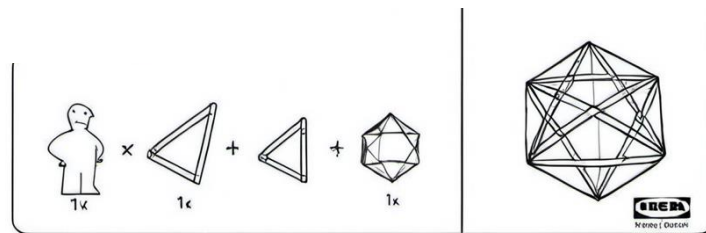
<sup>[2]</sup> `release-2025.04-public/config`

<sup>[3]</sup> `--enable-comin --enable-bundled-python=comin`, see exercises

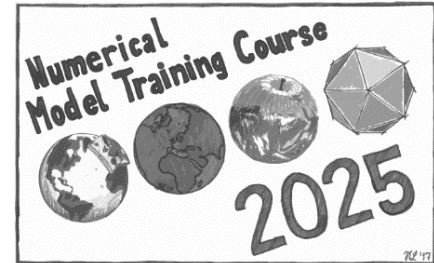
# Make some estimates for your simulation

- Do you aim at a global **computational grid**, a nested grid hierarchy or a regional scenario?
- What is the desired **spatial resolution**? First, estimate the grid size. The “RnBk Finder Tool” on the Zonda Web service<sup>[1]</sup> is a helpful resource for finding the desired grid size/bisection value.
- Derive the **time step**,  $\Delta t_{\text{time}}$ , as described in Sec 3.7 of the ICON tutorial.
- What are the **queue limits for your HPC**? For example, what is the maximum number of nodes per job and the maximum wall clock time (Slurm: `sinfo`)? ICON scales well with the number of MPI processes. Therefore, we will need these numbers later to determine the optimal setup for your simulation and hardware.
- Take your time and make a few notes! 

<sup>[1]</sup> <https://docs.icon-model.org/tools/tools.html#ref-tools-gridextpargui>



# Gather your data



# Generate a suitable grid

- Use the **Zonda Web service**<sup>[1]</sup> to generate the grids and external parameter sets – all you need is a Github account. Grids on the same level are always (automatically) disjoint! Save the log files and Fortran namelist parameters for later, as these will document your setup.
- You might also make use of the list of pre-defined grids<sup>[2]</sup>.
- Consider introducing a **reduced radiation grid** (domain 0), i.e., using a coarser horizontal grid for radiation than for dynamics. See Section 3.10 of the ICON tutorial for details and related Fortran namelist settings.
- In many cases, you can use a regional grid from a nested grid hierarchy for limited-area simulations, and vice versa. Note, however, that this is no longer compatible when using a reduced radiation grid.
- Advanced tip if you have access to the DWD ICON Tools: Post-process the grid with the “icon\_delaunay” tool (barycentric interpolation, but ICON also supports on-the-fly calculation).

<sup>[1]</sup> <https://docs.icon-model.org/tools/tools.html#ref-tools-gridextpargui>

<sup>[2]</sup> [http://icon-downloads.zmaw.de/dwd\\_grids.xml](http://icon-downloads.zmaw.de/dwd_grids.xml)

# Initial and boundary data from DWD

- The simplest option is the **Initialized Analysis** product (single file only, containing the analyzed state). This data can be retrieved using DWD's web-based PAMORE service<sup>[1]</sup>. The downside: Access to PAMORE comes with a small fee and some bureaucracy.
- A list of mandatory and optional **input fields** can be found in Section 11.4, “Analysis Products”, and Section 2.3, “Boundary Data Preparation”, of the ICON Tutorial. Remember that it makes no sense to remap tiled surface datasets!
- Appropriate temporal frequency of **boundary data** is important. For most of our real data NWP simulations, we choose a frequency of between 3 and 6 hours.
- Make a test with `grib_ls` and `cdo sinfov`, checking if you have the GRIB2 definitions set up properly. For example, when your surface pressure is labelled as `sp...` then you missed some environment setting (should be `PS`).

<sup>[1]</sup> <https://www.dwd.de/DE/leistungen/pamore/pamore.html>

# Interpolate the data onto the computational grid

- As in our practical exercises, we recommend choosing **NetCDF** as the target file format for interpolation.
- We recommend the well-maintained **cdo tools** (Climate Data Operators). See, eg., the script `exercise_prepare_lam/scripts/remap_inidata_iconremap.ipynb` from the practical exercises.
- By the way: This would be a good point where you could make a first visualization (we suggest to use Python and `cartopy`). The simple visual check clarifies whether we have made any technical errors in the previous steps.



# Interpolate the data onto the computational grid

Be careful: The greater the (spatial) **resolution jump** between the input data and the computational grid, the greater the potential spin-ups / spin-downs in different variables.

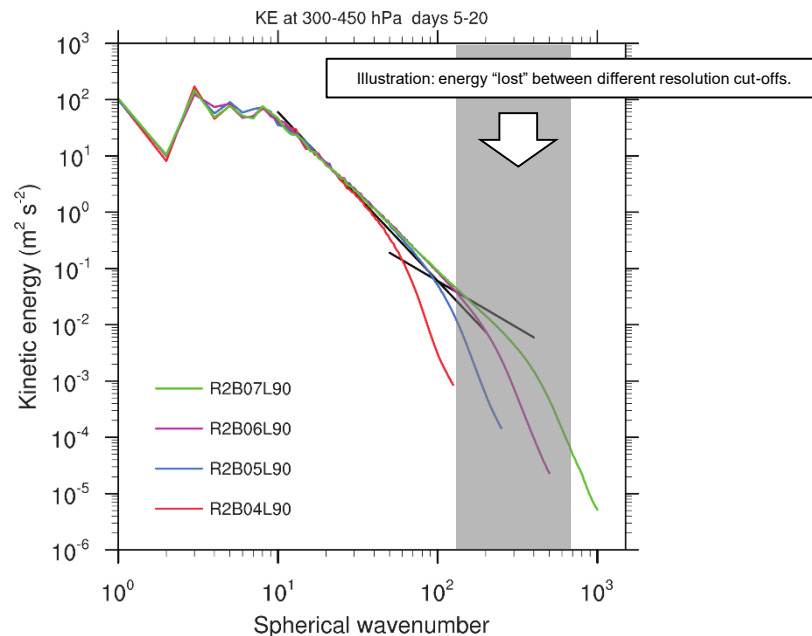
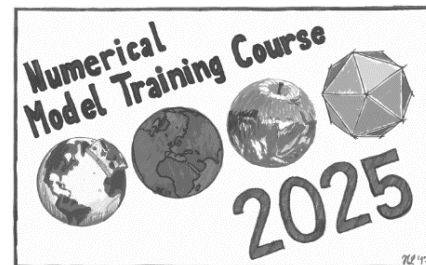


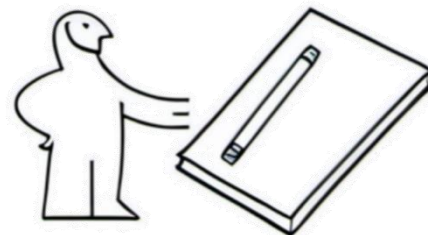
Fig. 7 from: Zängl, G., Reinert, D., Rípodas, P. and Baldauf, M. (2015), The ICON (ICOsahedral Non-hydrostatic) modelling framework of DWD and MPI-M: Description of the non-hydrostatic dynamical core. Q.J.R. Meteorol. Soc., 141: 563-579. <https://doi.org/10.1002/qj.2378>

# Namelist setup and test run



# Construct your Fortran namelist setup

- As a starting point: Begin with one of ICON's run script tools<sup>[1]</sup>. A **run-script** sets up the working directory, populates it with all required input files (grid files, namelists, etc.), sets environment variables, and runs the model.
- Here, we suggest to use the `make_runscript` tool, which is usually used to generate regression tests from the `run` sub-directory. Alternatively, you might start from one of the test setups from this ICON course.
- For **specific Fortran namelist settings** consider the table in `doc/Namelist_overview/Namelist_overview.pdf`, the documentation on <https://docs.icon-model.org> and the ICON tutorial!



<sup>[1]</sup> [https://docs.icon-model.org/buildrun/buildrun\\_running.html#using-make-runscript-to-prepare-icon-experiments](https://docs.icon-model.org/buildrun/buildrun_running.html#using-make-runscript-to-prepare-icon-experiments)

# Construct your Fortran namelist setup (cont'd)

From the perspective of a computational scientist with a focus on dynamics and infrastructure:

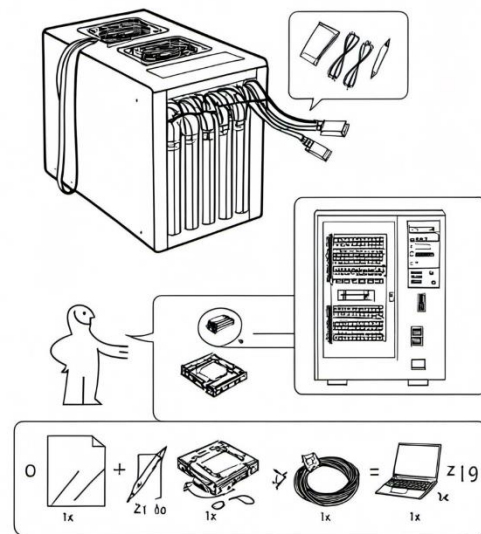
Namelist Name	Purpose
master_nml	Controls restart information
master_model_nml	Contains model-specific information, including model type, and associated namelist files
master_time_control_nml	Manages calendar information, start/stop dates, and restarts
run_nml	Specifies time integration settings, model processes, and tracer configuration
grid_nml	Contains grid configuration details
extpar_nml	Provides external parameter settings
sleve_nml	Sets vertical coordinate information
initicon_nml	Determines the mode of initialization
nonhydrostatic_nml	Configures parameters for the nonhydrostatic dynamic core
parallel_nml	Handles parallel computing and vectorization settings
transport_nml	Manages transport scheme parameters

But you shouldn't forget about `physics_nml`, `tuning_nml`, `soil_nml`, `turbulence_nml` ...!

# Construct your Fortran namelist setup (cont'd)

- To make things easier, it's best to keep all the input files and the ICON binary in one place, linked together (use the `ln -s` command) or as a copy. Make sure to have plenty of space available in your **experiment/output directory**.
- Initial data files are typically required for each nested domain. This can be overcome with only a slight loss of forecast skill by starting the nested domain(s) shortly after the global domain. See the Fortran namelist parameters `start_time` and `end_time`.
- Modify your Fortran namelist to have a **short run-time**.
- Having launched `cd ${RUNDIR} && sbatch icon.sbatch`, keep your fingers crossed and get yourself a ☕ coffee!

## SUPERCÖMER



The logo  
Tarses oomwitten rapable arende is-ile uical oomwitten ab ools  
It's a paperthin icon. It's not a paperthin icon.

# Check the results for technical plausibility

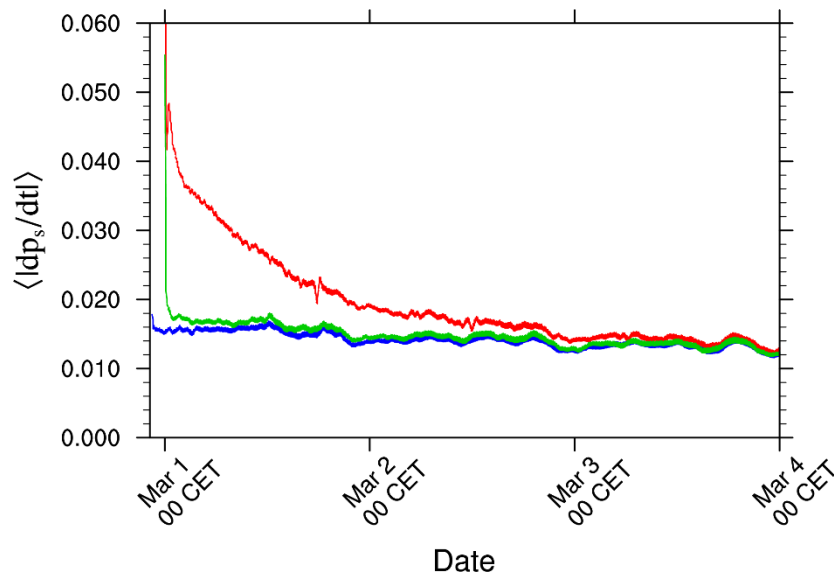
- Check the **log files**, as you have two: `stderr` and `stdout`. However, ICON intentionally writes its output to the standard error stream. Messages sent to `stderr` are less likely to be buffered and appear immediately in terminal windows or job logs.
- Take a look at the average cells/process: `Information on domain decomposition ... prognostic cells: max/min/avg`. The ratio of cells to halo cells is an important factor in assessing the efficiency of MPI communication.
- As before, make a quick visual check of your data (visualization script).
- Examine the table of ICON internal **sub-process timers** located at the end of the log file. Are there any dominant sub-processes, or is there an imbalance between them? Additionally, the MPI runtime often concludes with an “MPI Program Information” message containing helpful job information.

# Check the results for technical plausibility

Monitor the area-averaged absolute **surface pressure** tendency  $\left| \frac{dp_s}{dt} \right|$ . This should decrease quickly during the start-up phase of your experiment and should not increase significantly at later lead times.

- Note: requires namelist setting  
`run_nml::msg_level ≥ 11`

Source: ICON Tutorial, Section “Necessary Input Data/Initial Conditions”, [initialized analysis](#)



# Refine your experiment setup

- Enable/change the settings for the **physical parameterizations**. However, be careful: Not all Namelist options can be combined at random. For example
  - Convection is switched on in the parent grid but switched off in the nested child grid: This does not make much sense (see the lecture on Tuesday)
  - Only use the 2-mom microphysics scheme at a resolution below 3 km: This scheme is most suitable at convection-permitting or convection-resolving scales.
  - Do not change the microphysics between domains (the 2-mom microphysics scheme requires different tracers).
- Note: Changing the resolution and parameterisations will most probably affect the settings in the `tuning_nml`.



# Refine your experiment setup (cont'd)

- Set the actual **start and end date** for the experiment in the `time_nml` namelist (`ini_datetime_string`, `end_datetime_string`).
- Using the information about the HPC, extrapolate the actual simulation times from the measured runtimes of your short test run.
- Adjust the **wallclock limit** and the **number of nodes** in your run-script, the number of tasks per node, and (implicitly) the total number of MPI tasks (Slurm: `#SBATCH --nodes=xxx`, `#SBATCH --ntasks-per-node=yyy`).
- You can control how many threads OpenMP creates by setting the environment variable `OMP_NUM_THREADS`.
- You can tune the memory consumption per node in a hybrid MPI and OpenMP job by adjusting the ratio between MPI tasks and OpenMP threads: using fewer MPI tasks per node and more OpenMP threads per task typically reduces total memory usage.

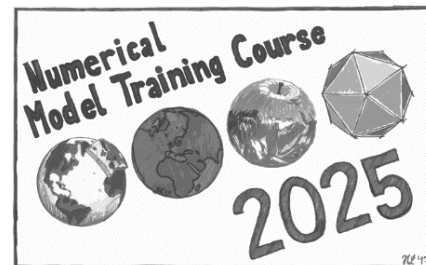
# Refine your experiment setup (cont'd)

- Based on the extrapolation of your test run and the queue limits on your HPC, define the **restart checkpointing**. See Section 7.2 of the ICON tutorial for details on checkpointing and restart.
- Regarding the available **output products**: See the ICON tutorial appendix or the ICON Database Reference Manual<sup>[1]</sup>; check if it makes sense for you to enable whole variable groups with the `group:` keyword.
- Is the asynchronous output working for you? The file `output_schedule.ps` contains a rudimentary visualization of write and idle times for the different output processes.
- Consider other output mechanisms, such as output via the YAC coupler<sup>[2]</sup>.
- If you need to understand advanced topics such as heterogeneous execution and GPU accelerators: Seek out an expert!


<sup>[1]</sup> [https://www.dwd.de/SharedDocs/downloads/DE/modelldokumentationen/nwv/icon/icon\\_dbbeschr\\_aktuell.html](https://www.dwd.de/SharedDocs/downloads/DE/modelldokumentationen/nwv/icon/icon_dbbeschr_aktuell.html)

<sup>[2]</sup> see [https://www.nat-esm.de/services/workshops-and-trainings/technical-trainings/20240717\\_natesm\\_a\\_pythonic\\_way\\_to\\_use\\_yac\\_dreier.pdf](https://www.nat-esm.de/services/workshops-and-trainings/technical-trainings/20240717_natesm_a_pythonic_way_to_use_yac_dreier.pdf)

Follow your own path!



# Follow your own path!

- The **ICON Community Interface**, ComIn), has been designed as a stable interface for third-party plugins<sup>[1]</sup>. Is ComIn sufficient for your needs?
- Otherwise: Get ready for the big adventure! Make sure that you are familiar with the `jc`, `jb` blocked layout of ICON arrays. Find out about how grids are stored, how parallel communication works in ICON. Etc.
- Write your own feature for the ICON model! 

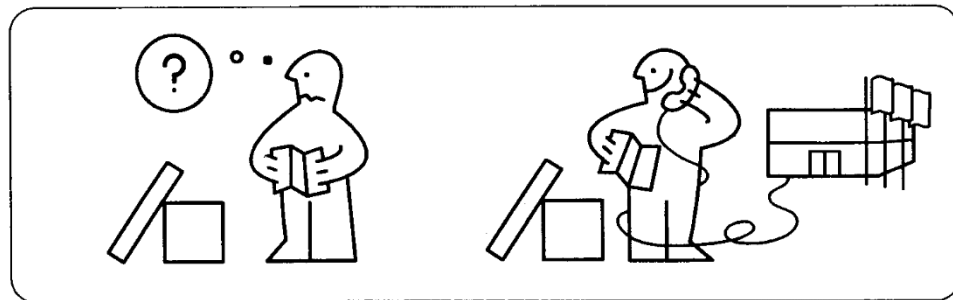
<sup>[1]</sup> <https://gitlab.dkrz.de/icon-comin/comin>

# If something went wrong ...

- If the build or configuration process fails, check the individual build sub-processes of the external libraries and build them one by one (always check the final paragraphs of the respective `config.log` file).
- Grids, constant data etc. are associated by `uuidOfHGrid` metadata. Check for consistency!
- If your program aborts, do not stop reading when you see a “SegFault” error message. This may only be a secondary error. Try to find the actual error message and stack trace.
- Log messages on maximum wind speed (`MAXABS VN, W`): how quickly do these values grow? Which domain and model level? This could, for example, indicate insufficient Rayleigh damping at TOA.
- Check the time-stepping output log for messages about the calling of physical modules (e.g. `downscaling of radiation output fields`). Does the calling frequency correspond to the intended namelist settings? In case of an error: Does the log message indicate where the error occurred?

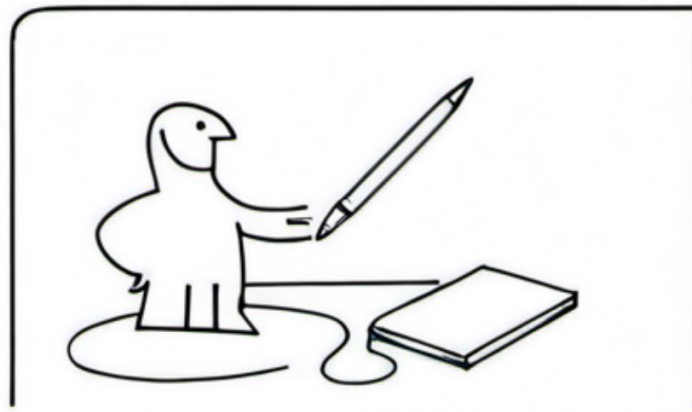
# If something went wrong: Seek for help!

- Carefully re-read what you can find about your case on <https://docs.icon-model.org/> and in the ICON tutorial.
- Who's the ICONist in your department? Get on his nerves!
- Double-check the time step `dtime` and decrease it if in doubt
- Build the ICON executable binary with enhanced debugging options, eg. enable array bounds checking for your compiler (GNU compiler: `-fcheck=bounds`).



# In the unlikely event of success

- Don't hide your findings, suggestions, or observed bugs!
- Be persistent! When you are interested in a collaboration, try to find the right ICON institute and developers
- Whom to contact? Try to find out about author information (`git blame`).



# Final words

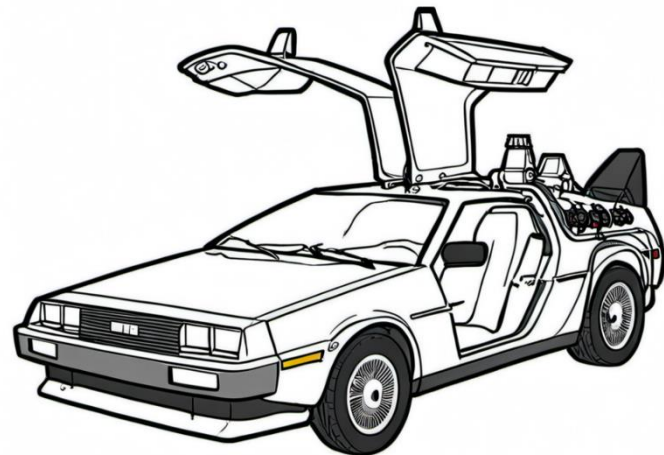


# Final words

Over the past few years, various machine learning surrogate models have been announced.

- They claim to produce better forecast scores while using fewer hardware resources.
- Almost certainly these ML-based models will become part of the operational NWP process chain, eg. for real-time impact forecasts.
- Nevertheless, they have limited interpretability and do not yet offer predictions on a comparable number of vertical levels. They also lack forecast variability and sometimes physical consistency.
- ML models are still based on reanalysis data sets of “classical” grid point models.

These arguments should make it clear that the ICON model will remain relevant in the future.



# Evaluation of the training

- With these concluding remarks, this training course ends.
- We hope that we have given you some ideas and, most importantly, some things to get you thinking about what you want to do next with ICON.
- Please take part in our survey - for an improved ICON training next year!
- Fill out the form: <https://forms.gle/UJT5KVgTXrAinCa6>





## **Florian Prill**

Met. Analyse und Modellierung  
Deutscher Wetterdienst

e-mail: [Florian.Prill@dwd.de](mailto:Florian.Prill@dwd.de)