# **ICON Community Interface "ICON ComIn"**

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# What are the applications of ComIn?

First ideas for use cases of the ComIn generalized interface to ICON:

- connect ICON to e.g. wave model, chemistry components, ocean model
- couple external models e.g. via YAC
- interface ICON variables with other frameworks, e.g. ECMWF's At library, and with other programming languages like C/C++
- embed Python scripts, execute during the simulation
- (interpolated) model I/O
- additional diagnostics

# ... and what is ComIn?

The community interface organizes the inclusion of simulation even a plugin to ICON and sharing of data between the two. ComIn is not coupler but the interface controls what, how and when foreign func are called within ICON and data is exposed or exchanged. ComIn is a developed by DWD, DLR, DKRZ and FZJ with consultative contributio from KIT.

## Software prototype

- implemented in Fortran but interface design open for plugins in a languages through ISO-C bindings
- ComIn requires publishing a small part of ICON data structures in adapter library
- YAC adapter as one example ComIn plugin
- general aim: Open Source license

# **Design concept overview**

- version and compatibility handling (backward compatibility)
- adapter library
  - read/write access to ICON variables
  - descriptive data structures shared from ICON
  - (grid, parallelization info, simulation time stamp, ...) • plugins can create additional variables
- callback register, definition of entry points
- build process (independent from ICON's build process)



Schematic 1: The adapter library controls exchange of variables between ICON and plugins connected via ComIn.

## **Specifics of the adapter library (at least for v1.0)** Roadmap

- 1. Finish the **prototype** (standalone version) ~ Q2/23 2. Initiate an internal **review phase** • interfaces, definition of entry points, documentation ICON (information on location of vertical and blocking indices provided) • fill mockup with "real information" in ICON feature branch 3. Test use of ICON via ComIn in first test application(s). Some further decisions, e.g. testing procedure for external modules, are guarding against "malicious" write access open.
- Request POINTERs to ICON variables for specific entry points. • ComIn interfaces are restricted to cell-based variables blocked, process-local variable arrays are exposed as they are stored in • multiple computational domains supported no variables with multiple time levels (instead POINTER swapping) • plugins can READ, WRITE or READ/WRITE ICON variables, no safe-• plugins cannot change restart flag to ICON's standard fields Plugins can also create additional variables (surface or 3D, tracers possible, can be requested exclusively, registration for inclusion in restart files).

	How are the descriptive data organized?			How can ComIn be integrated into your application?
	Descriptive data structures contain information on the ICON setup, the computational grid(s), and the simulation status. They are part of the adapter library.			Primary constructor of plugin A
or land				<b>SUBROUTINE</b> plugin_modA_setup(lrestart, comin_setup_version_info_out, ie
				LOGICAL, INTENT(IN) :: lrestart
tlas	<ul> <li>all descriptive data structures</li> <li>global data (o g Fortrap KIND</li> </ul>	s are read-only	mmunicator) and grid	TYPE(t_comin_setup_version_info), INTENT(OUT) :: comin_setup_version_ INTEGER INTEGER
	<ul> <li>global data (e.g. Fortrain KiND values, WFF communicator) and grid information are available from the primary constructor</li> <li>simulation status available from the secondary constructor</li> <li>references (POINTERs) are preferred over values (copies), efficiency vs. safe-guarding against "malicious" write access</li> </ul>			
				<b>INCLUDE</b> "comin_version_info.f90"
				remin cotum ucucion info out - comin cotum ucucion info
				ierr = 0
			COMMUNITY INTERFACE	<pre>IF (comin_setup_version_info%version_no_major &gt; 1) THEN</pre>
	Model Init			ierr = 1; RETURN
		entry points	function callbacks	
tions			plugin A	CALL get_comin_parallel_info(info)
actively			plugin B	
ons	Dynamics			<pre>'CALL comin_setup_activate_plugin(pluginname, plugin_setup, wp, ierr)  'IF (ierr /= 0) RETURN</pre>
			$\times$	
	Tracer Advection			<pre>CALL comin_request_add_var(t_comin_var_descriptor(jg = 1, &amp; &amp;</pre>
other	East Physics		plugin B	&     name = "myvariable"), t_comin_var_metadata( & ]       &     ltracer = .FALSE lmodexclusive = .FALSE & ]
				&   Irestart = .FALSE., itype_vlimit = 1,   &
			plugin A	<pre>&amp; itype_hlimit = 4, is_3d_field = .TRUE.), ierr)</pre>
	Slow Physics			IF (ierr /= 0) RETURN
			plugin A	<b>CALL</b> comin callback register (EP SECONDARY CONSTRUCTOR, my constructor
	Output		plugin B	<b>CALL</b> comin_callback_register(EP_BEFORE_WRITE_OUTPUT, my_diagfct, ie
				p patch => comin descrdata get patch grid info(1)

Schematic 2: Callbacks of plugins registered via ComIn are called at specified entry points within ICON.

# How are callbacks organized?

Functions from plugins may be called at pre-defined events during a model simulation. One CALL in ICON handles execution of all registered plugins for one entry point. All function callbacks need to be registered in the primary constructor.

- two entry points before the time loop (see details on the right)
- primary constructor
- secondary constructor (optional, needs to be registered in primary constructor, called after allocation of ICON variable list and before time loop)
- several entry points during the **time loop** • all entry points above the "block loop level"

**SUBROUTINE** my constructor() var desc%name = 'press' var desc%jg = CALL comin\_var\_get(EP\_BEFORE\_WRITE\_OUTPUT, var\_desc, FLAG\_SYNCHRONIZED, press) var desc%name = 'temp CALL comin\_var\_get((/EP\_SECONDARY\_CONSTRUCTOR, EP\_BEFORE\_ADVECTION/), & & var\_desc, FLAG\_SYNCHRONIZED, temp) **END SUBROUTINE** my constructor

Nth callback of plugin A

**SUBROUTINE** my diagfct() WRITE (0,\*) "data in callback:", press%ptr(1,1,1,1,1) END SUBROUTINE my diagfct

**Entry point in ICON** 

#ifdef HAVE COMIN !> example of a third-party entry point (callback) CALL comin\_callback\_context\_call(EP\_BEFORE\_ADVECTION)
#endif /\* ifdef HAVE\_COMIN \*/

Using **dynamic linking** of plugins (recommended approach): 1. Build ICON ComIn. 2. Build plugins (linking against ComIn library). 3. Specify plugins for primary constructor in *comin\_nml*. Generates primary constructor calls automatically. 4. Build ICON with ComIn (--with-comin=\${ICON\_COMIN\_DIR} during configure).



\_ \_ \_ \_ \_ , ierr) err)

**END SUBROUTINE** plugin\_modA\_setup

Secondary constructor of plugin A

**Build process** 

Alternative build process using statically linked libraries: In the third step the plugin, which should be statically linked, is not itself specified but "icon" is set as plugin. This allows (though with some effort) to link individual libraries statically to ICON.





# +Omin-

err)

info out

return ComIn version with which this module was built to ICON

check own compatibility with ComIn version

register plugin

request additional ICON variable

register function callbacks get descriptive data

structures, e.g. grid information

get pointer to ICON variable, updated at two entry points with **READ/WRITE** intent (synchronized)

data access through previously stored POINTERs

preprocessor directives encapsulate ComIn calls

one CALL for all plugins





